

7.7 Fundamental Matrices

Consider the system $\vec{x}' = A\vec{x}$ where $A = \begin{bmatrix} 1 & 1 \\ 4 & -2 \end{bmatrix}$

The eigenvalues and eigenvectors of this system are

$$\begin{aligned} \lambda_1 &= 2 & \vec{x}^{(1)} &= \begin{bmatrix} 1 \\ 1 \end{bmatrix} \\ \lambda_2 &= -3 & \vec{x}^{(2)} &= \begin{bmatrix} 1 \\ -4 \end{bmatrix} \end{aligned}$$

So a fundamental set of solution is

$$\vec{x}^{(1)}(t) = \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{2t} = \begin{bmatrix} e^{2t} \\ e^{2t} \end{bmatrix} \quad \vec{x}^{(2)}(t) = \begin{bmatrix} 1 \\ -4 \end{bmatrix} e^{-3t} = \begin{bmatrix} e^{-3t} \\ -4e^{-3t} \end{bmatrix}$$

and the general solution is $\vec{x} = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{2t} + c_2 \begin{bmatrix} 1 \\ -4 \end{bmatrix} e^{-3t}$

We define the fundamental Matrix $V(t)$ for this problem to be

$$V(t) = \begin{bmatrix} \vec{x}^{(1)}(t) & \vec{x}^{(2)}(t) \end{bmatrix} = \begin{bmatrix} e^{2t} & e^{-3t} \\ e^{2t} & -4e^{-3t} \end{bmatrix}$$

Since $\vec{x}^{(1)'} = A\vec{x}^{(1)}$ and $\vec{x}^{(2)'} = A\vec{x}^{(2)}$ we have

$$\boxed{V'(t) = AV(t)}$$

If an initial condition $\vec{x}^0$ is available then $\vec{x}^0 = c_1 \vec{x}^{(1)}(0) + c_2 \vec{x}^{(2)}(0)$
or

$$\boxed{\vec{x}^0 = V(0) \vec{c}} \quad \text{where } \vec{c} = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

This also lets us write the solution at time t as $\boxed{\vec{x}(t) = V(t) \vec{c}}$

We know that $V(t)$ is invertible (why? - its columns are the linearly independent solution vectors). Thus

$$\vec{c} = V(0)^{-1} \vec{x}^0$$

Which means, in turn, that

$$\vec{x}(t) = V(t) V(0)^{-1} \vec{x}^0$$

Ex Suppose $\vec{x}^0 = \begin{bmatrix} 1 \\ 6 \end{bmatrix}$ for our problem. Then

$$V(0) \vec{c} = \begin{bmatrix} 1 \\ 6 \end{bmatrix} \rightarrow \begin{bmatrix} e^0 & e^0 \\ e^0 & -4e^0 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & -4 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 6 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & -4 & 6 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 \\ 0 & -5 & 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & -1 \end{bmatrix} \text{ so } \vec{c} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

$$\therefore \vec{x}(t) = \begin{bmatrix} e^{2t} & e^{-3t} \\ e^{2t} & -4e^{-3t} \end{bmatrix} \begin{bmatrix} 2 \\ -1 \end{bmatrix} = 2 \begin{bmatrix} e^{2t} \\ e^{2t} \end{bmatrix} - \begin{bmatrix} e^{-3t} \\ -4e^{-3t} \end{bmatrix}$$

Note that using $V(t)$ does not save us any work - it only provides a different way to represent the solution.

The matrix $V(t)$ for a given problem is not unique - its columns consist of any n linearly independent solution vectors to the linear system.

In particular, $\phi(t) = V(t) V(0)^{-1}$ is also a fundamental matrix for $\vec{x}' = A\vec{x}$ if $V(t)$ is a fundamental matrix:

$$A\phi(t) = A V(t) V(0)^{-1} = V'(t) V(0)^{-1} = (V(t) V(0)^{-1})' = \phi'(t) \Rightarrow \phi'(t) = A\phi(t)$$

We can find $\phi(t)$ by forming $V(t)V^{-1}(0)$, but this requires finding the inverse of an $n \times n$ matrix. This may be worthwhile, however, if the problem

$$\begin{cases} \vec{X}' = A\vec{X} \\ \vec{X}(0) = \vec{X}^0 \end{cases}$$

must be solved for several different initial conditions $\vec{X}^0$. This is because the solution $\vec{X}(t)$ is given by

$$\vec{X} = \phi(t) \vec{X}^0$$

only requiring a matrix-vector multiplication, rather than solving

$$V(0) \vec{c} = \vec{X}^0$$

and then computing

$$\vec{X} = V(t) \vec{c}.$$

Finally note that the columns of $\phi(t)$ can be computed by solving $V(0) \vec{c}^{(i)} = \vec{e}^{(i)}$ for $i=1, \dots, n$ and then forming $\vec{\phi}^{(i)} = V(t) \vec{c}^{(i)}$

Ex $\begin{bmatrix} 1 & 1 \\ 1 & -4 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \rightarrow \vec{c}^{(1)} = \begin{bmatrix} 4/5 \\ 1/5 \end{bmatrix} \quad \vec{\phi}^{(1)} = \begin{bmatrix} e^{2t} & e^{-3t} \\ e^{2t} & -4e^{-3t} \end{bmatrix} \begin{bmatrix} 4/5 \\ 1/5 \end{bmatrix} = \frac{1}{5} \begin{bmatrix} 4e^{2t} + e^{-3t} \\ 4e^{2t} - 4e^{-3t} \end{bmatrix}$

$$\begin{bmatrix} 1 & 1 \\ 1 & -4 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \rightarrow \vec{c}^{(2)} = \begin{bmatrix} 1/5 \\ -1/5 \end{bmatrix} \quad \vec{\phi}^{(2)} = \begin{bmatrix} e^{2t} & e^{-3t} \\ e^{2t} & -4e^{-3t} \end{bmatrix} \begin{bmatrix} 1/5 \\ -1/5 \end{bmatrix} = \frac{1}{5} \begin{bmatrix} e^{2t} - e^{-3t} \\ e^{2t} + 4e^{-3t} \end{bmatrix}$$

$$\text{So } \phi(t) = \frac{1}{5} \begin{bmatrix} 4e^{2t} + e^{-3t} & e^{2t} - e^{-3t} \\ 4e^{2t} - 4e^{-3t} & e^{2t} + 4e^{-3t} \end{bmatrix}$$